

11 Panel Data

11.1 Wang (2003) estimator

$$\begin{aligned}
0 &= \sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \left\{ \begin{array}{l} \sigma^{tt} \left[y_{it} - \widehat{m}_{[l]}(\mathbf{x}) - \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \widehat{\beta}_{[l]}(\mathbf{x}) \right] \\ + \sum_{\substack{s=1 \\ s \neq t}}^{T_i} \sigma^{st} \left[y_{is} - \widehat{m}_{[l-1]}(\mathbf{x}_{is}) \right] \end{array} \right\} \\
&= \sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \left\{ \begin{array}{l} \sigma^{tt} y_{it} + \sum_{\substack{s=1 \\ s \neq t}}^{T_i} \sigma^{st} y_{is} \end{array} \right\} \\
&\quad - \sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \left\{ \begin{array}{l} \sigma^{tt} \left[\widehat{m}_{[l]}(\mathbf{x}) + \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \widehat{\beta}_{[l]}(\mathbf{x}) \right] \\ \sum_{\substack{s=1 \\ s \neq t}}^{T_i} \sigma^{st} \widehat{m}_{[l-1]}(\mathbf{x}_{is}) \end{array} \right\}
\end{aligned}$$

Combining like terms and moving the second term to the left-hand-side of zero gives

$$\begin{aligned}
&\left[\sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \sigma^{tt} \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \left(1 \quad \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \right] \begin{pmatrix} \widehat{m}_{[l]}(\mathbf{x}) \\ \widehat{\beta}_{[l]}(\mathbf{x}) \end{pmatrix} \\
&= \left[\sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \right] \left[\begin{array}{l} \sigma^{tt} y_{it} + \sum_{\substack{s=1 \\ s \neq t}}^{T_i} \sigma^{st} (y_{is} - \widehat{m}_{[l-1]}(\mathbf{x}_{is})) \end{array} \right]
\end{aligned}$$

and hence

$$\begin{aligned}
\begin{pmatrix} \widehat{m}_{[l]}(\mathbf{x}) \\ \widehat{\beta}_{[l]}(\mathbf{x}) \end{pmatrix} &= \left[\sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \sigma^{tt} \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \left(1 \quad \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \right]^{-1} \\
&\quad \times \left[\sum_{i=1}^n \sum_{t=1}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{1}{\frac{\mathbf{x}_{it}-\mathbf{x}}{h}} \right) \right] \left[\begin{array}{l} \sigma^{tt} y_{it} + \sum_{\substack{s=1 \\ s \neq t}}^{T_i} \sigma^{st} (y_{is} - \widehat{m}_{[l-1]}(\mathbf{x}_{is})) \end{array} \right].
\end{aligned}$$

11.2 Henderson, Carroll and Li (2008) estimator

The algorithm is linear in the y_{it} 's. By defining

$$H_{i,[\ell-1]} = \begin{pmatrix} y_{i2} - \widehat{m}_{[\ell-1]}(\mathbf{x}_{i2}) \\ \vdots \\ y_{iT_i} - \widehat{m}_{[\ell-1]}(\mathbf{x}_{iT_i}) \end{pmatrix} - \{y_{i1} - \widehat{m}_{[\ell-1]}(\mathbf{x}_{i1})\} \mathbf{i}_{T_i-1},$$

we get

$$\begin{aligned} 0 &= \sum_{i=1}^n K_h(\mathbf{x}_{i1}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \end{pmatrix} \left[+\mathbf{i}'_{T_i-1} V^{-1} \mathbf{i}_{T_i-1} \left\{ \widehat{m}_{[\ell-1]}(\mathbf{x}_{i1}) - \begin{pmatrix} 1 & \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \end{pmatrix} \begin{pmatrix} \alpha_0 \\ \alpha_1 \end{pmatrix} \right\} \right] \\ &+ \sum_{i=1}^n \sum_{t=2}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \end{pmatrix} \left[+c'_{t-1} V^{-1} c_{t-1} \left\{ \widehat{m}_{[\ell-1]}(\mathbf{x}_{it}) - \begin{pmatrix} 1 & \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \end{pmatrix} \begin{pmatrix} \alpha_0 \\ \alpha_1 \end{pmatrix} \right\} \right]. \end{aligned}$$

Solving for α_0 and α_1 leads to $\{\widehat{\alpha}_0(\mathbf{x}), \widehat{\alpha}_1(\mathbf{x})\}' = D_1^{-1} (D_2 + D_3)$

$$\begin{aligned} D_1 &= n^{-1} \sum_{i=1}^n \left\{ \begin{array}{l} \mathbf{i}'_{T_i-1} V^{-1} \mathbf{i}_{T_i-1} K_h(\mathbf{x}_{i1}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \end{pmatrix} \begin{pmatrix} 1 & \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \end{pmatrix} \\ + \sum_{t=2}^{T_i} c'_{t-1} V^{-1} c_{t-1} K_h(\mathbf{x}_{it}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \end{pmatrix} \begin{pmatrix} 1 & \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \end{pmatrix} \end{array} \right\}; \\ D_2 &= n^{-1} \sum_{i=1}^n \mathbf{i}'_{T_i-1} V^{-1} \mathbf{i}_{T_i-1} K_h(\mathbf{x}_{i1}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \end{pmatrix} \widehat{m}_{[\ell-1]}(\mathbf{x}_{i1}) \\ &+ \sum_{t=2}^{T_i} c'_{t-1} V^{-1} c_{t-1} K_h(\mathbf{x}_{it}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \end{pmatrix} \widehat{m}_{[\ell-1]}(\mathbf{x}_{it}); \\ D_3 &= n^{-1} \sum_{i=1}^n \left\{ \begin{array}{l} \sum_{t=2}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \end{pmatrix} c'_{t-1} V^{-1} H_{i,[\ell-1]} \\ - K_h(\mathbf{x}_{i1}, \mathbf{x}) \begin{pmatrix} 1 \\ \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \end{pmatrix} \mathbf{i}'_{T_i-1} V^{-1} H_{i,[\ell-1]} \end{array} \right\}, \end{aligned}$$

The next step estimate of $m(\mathbf{x})$ is given by $\widehat{m}_{[\ell]}(\mathbf{x}) = \widehat{\alpha}_0(\mathbf{x})$.

The particular form of our problem means that many of the terms have simple expressions.

In particular,

$$\begin{aligned}
\mathcal{L}_{i,11m} &= -e'_{t-1}V^{-1}e_{t-1} = -(T_i - 1)/(T_i\sigma_v^2); \\
\mathcal{L}_{i,ttm} &= -c'_{t-1}V^{-1}c_{t-1} = -(T_i - 1)/(T_i\sigma_v^2) \quad \text{for } t \geq 2; \\
\mathcal{L}_{i,1tm} &= -c'_{t-1}V^{-1}e_{m-1} = -\frac{1}{T_i\sigma_v^2} \quad \text{for } t \geq 2; \\
\mathcal{L}_{i,tsm} &= -c'_{t-1}V^{-1}c_{s-1} = \frac{1}{T_i\sigma_v^2} \quad \text{for } t, s \geq 2 \text{ and } t \neq s;
\end{aligned}$$

If we incorporate these values, we can simplify our estimator as

$$\begin{aligned}
D_1 &= \frac{1}{n\sigma_v^2} \sum_{i=1}^n \left\{ \begin{aligned} &K_h(\mathbf{x}_{i1}, \mathbf{x}) \left(\frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \right) \left(1 \quad \frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \right) \\ &+ \sum_{t=2}^{T_i} \frac{(T_i-1)}{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \left(1 \quad \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \end{aligned} \right\}; \\
D_2 &= \frac{1}{n\sigma_v^2} \sum_{i=1}^n \left\{ \begin{aligned} &K_h(\mathbf{x}_{i1}, \mathbf{x}) \left(\frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \right) \widehat{m}_{[\ell-1]}(\mathbf{x}_{i1}) \\ &+ \sum_{t=2}^{T_i} \frac{(T_i-1)}{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \widehat{m}_{[\ell-1]}(\mathbf{x}_{it}) \end{aligned} \right\}; \\
D_3 &= \frac{1}{n} \sum_{i=1}^n \left\{ \begin{aligned} &\sum_{t=2}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) c'_{t-1} V^{-1} H_{i, [\ell-1]} \\ &- K_h(\mathbf{x}_{i1}, \mathbf{x}) \left(\frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \right) \mathbf{i}'_{T_i-1} V^{-1} H_{i, [\ell-1]} \end{aligned} \right\},
\end{aligned}$$

and this simplifies to

$$\begin{aligned}
D_1 &= \frac{1}{\sigma_v^2} \sum_{i=1}^n \sum_{t=1}^{T_i} \frac{(T_i-1)}{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \left(1 \quad \frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \\
D_2 &= \frac{1}{\sigma_v^2} \sum_{i=1}^n \sum_{t=1}^{T_i} \frac{(T_i-1)}{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) \widehat{m}_{[\ell-1]}(\mathbf{x}_{it}); \\
D_3 &= \sum_{i=1}^n \left\{ \begin{aligned} &\sum_{t=2}^{T_i} K_h(\mathbf{x}_{it}, \mathbf{x}) \left(\frac{\mathbf{x}_{it}-\mathbf{x}}{h} \right) c'_{t-1} V_i^{-1} H_{i, [\ell-1]} \\ &- K_h(\mathbf{x}_{i1}, \mathbf{x}) \left(\frac{\mathbf{x}_{i1}-\mathbf{x}}{h} \right) \mathbf{i}'_{T_i-1} V_i^{-1} H_{i, [\ell-1]} \end{aligned} \right\}.
\end{aligned}$$

11.3 Poolability test statistic

Following the logic from Chapter 6, we can construct a consistent test for poolability based on $E[uE(u|\mathbf{x})] = E\{[E(u|\mathbf{x})]^2\} \geq 0$ and the equality will hold if and only if the null is true. Again, we choose to estimate a density weighted version of $E[uE(u|\mathbf{x})]$ to avoid the random denominator problem in nonparametric estimation. The density weighted version of

$E[uE(u|\mathbf{x})]$ is given by

$$E\{uf(\mathbf{x})E[uf(\mathbf{x})|\mathbf{x}]f(\mathbf{x})\}.$$

The sample analogue of $uf(\mathbf{x})$ is

$$\hat{u}_{it}\hat{f}(\mathbf{x}_{it})$$

and that of $E(uf(\mathbf{x})|\mathbf{x})f(\mathbf{x})$ is

$$\frac{1}{(n-1)(h_1h_2\cdots h_q)}\sum_{\substack{j=1 \\ j\neq i}}^n\hat{u}_{jt}\hat{f}(\mathbf{x}_{jt})K_h(\mathbf{x}_{it},\mathbf{x}_{jt})$$

using n cross-sectional data for a fixed value of t . Hence, our test statistic is based on

$$\begin{aligned}\hat{J}_n &= \frac{1}{(nT-n)(h_1h_2\cdots h_q)}\sum_{i=1}^n\sum_{t=1}^{T_i}\hat{u}_{it}\hat{f}(\mathbf{x}_{it})\left\{\sum_{\substack{j=1 \\ j\neq i}}^n\hat{u}_{jt}\hat{f}(\mathbf{x}_{jt})K_h(\mathbf{x}_{it},\mathbf{x}_{jt})\right\} \\ &= \frac{1}{(nT-n)(h_1h_2\cdots h_q)}\sum_{i=1}^n\sum_{t=1}^{T_i}\sum_{\substack{j=1 \\ j\neq i}}^n\hat{u}_{it}\hat{f}(\mathbf{x}_{it})\hat{u}_{jt}\hat{f}(\mathbf{x}_{jt})K_h(\mathbf{x}_{it},\mathbf{x}_{jt}).\end{aligned}$$

Baltagi, Hidalgo and Li (1996) show that $n(h_1h_2\cdots h_q)^2\hat{J}_n$ is distributed normal, mean zero, with variance $2\sigma_0^2$ under the null. When the data are i.i.d. in the subscript i

$$\sigma_0^2 = \left[\int k^2(u)du\right]\left\{\sum_{t=1}^{T_i}\frac{1}{T_i^2}E[\sigma^4(\mathbf{x}_{1t})f^5(\mathbf{x}_{1t})]\right\},$$

and a consistent estimate of this unknown parameter can be obtained as

$$\hat{\sigma}_0^2 = \frac{1}{(nT-n)(h_1h_2\cdots h_q)}\sum_{i=1}^n\sum_{t=1}^{T_i}\sum_{\substack{j=1 \\ j\neq i}}^n\left[\hat{u}_{it}\hat{f}(\mathbf{x}_{it})\right]^2\left[\hat{u}_{jt}\hat{f}(\mathbf{x}_{jt})\right]^2K_h^2(\mathbf{x}_{it},\mathbf{x}_{jt})$$

Thus, the normalization

$$\hat{T}_n = \frac{n(h_1h_2\cdots h_q)^2\hat{J}_n}{\sqrt{2\hat{\sigma}_0^2}}$$

is distributed standard normal under the null.